

Differentiating Relational Queries

PhD Workshop at VLDB21

Paul Peseux

Tutors: T.Paquet, M.Berar, V.Nicollet



x



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Outline

- 1 Context
- 2 Formalization
- 3 Tables Relations
- 4 Automatic Differentiation
- 5 Implementation
- 6 Conclusion

Outline

1 Context

2 Formalization

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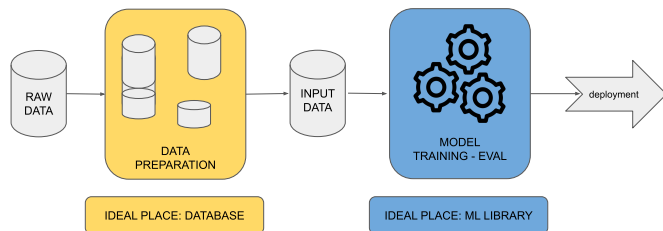


Figure: Classic Machine Learning Pipeline.

Context

- costly data transfer (Schüle 2019)
-

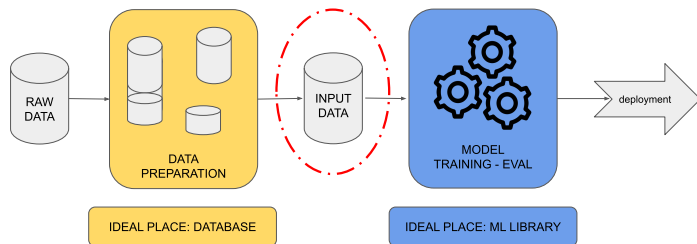


Figure: Classic Machine Learning Pipeline.

Context

- costly data transfer (Schüle 2019)
- ML libraries built for computer vision, NLP ...
→ **inadapted to relational data**

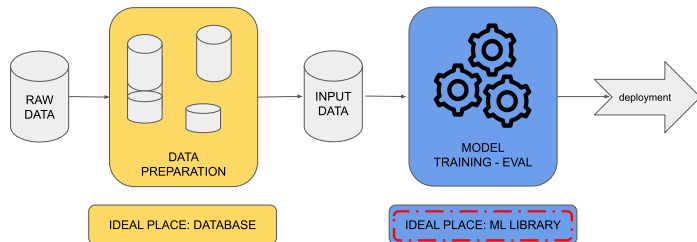


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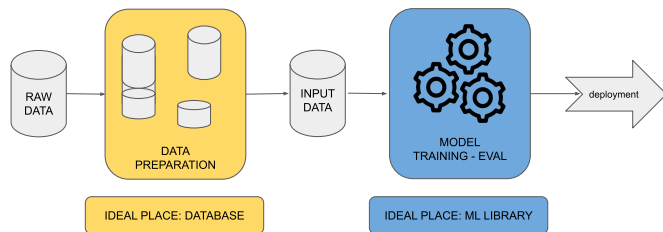


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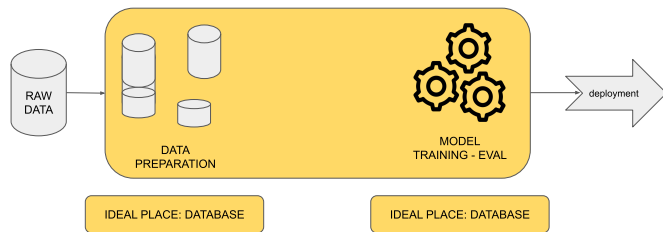


Figure: Proposed Pipeline.

Many Machine Learning methods are based on **gradient** methods.

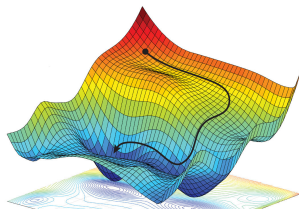


Figure: Gradient Descent, source (Hutson)

Many Machine Learning methods are based on **gradient** methods.

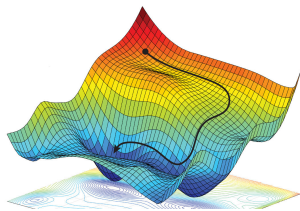


Figure: Gradient Descent, source (Hutson)

→ To optimize models, **relational queries differentiation** is missing (Schüle 2019)

Differentiating Relational Queries \Leftrightarrow Derivative of the Relational Queries



This is **not** differential dataflow (Mcsherry 2021)

```
SELECT X FROM Observations  
| | | should give  
SELECT 1 FROM Observations
```

```
SELECT X * X FROM Observations  
| | | should give  
SELECT 2 * X FROM Observations
```

Figure: What we are looking for

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Formalization

For the rest of the presentation, optimisation means minimisation and is allowed through gradient descent.

$$x^* = \underset{x}{\operatorname{arg\,min}} f(x)$$

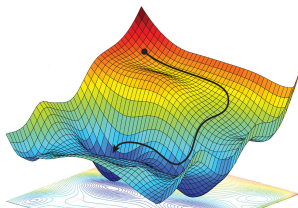


Figure: Gradient Descent, source (Hutson)

f is called *loss*

We want to minimize (*and thus compute the gradient of*):

```
SELECT sum(loss) FROM Observations
```

For that we need:

- a framework
- constraints on the query

Minimization is only possible on scalar.

$$Loss = \sum_{i \in Obs} loss_i = \sum_{i \in Obs} f(data_i)$$

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Constraint 1

Loss is computed line by line.

Example

Let's make it concrete with the Chicago taxi trip dataset.

Trips			
taxiid	Company	distance	Tips
d904764719c56cfb36906cb74c...	Choice Taxi Association	0.7	2.0
11f73b08790612efe341cf8cf69...	Choice Taxi Association	1.2	2.7
e61ce97d61bec30e506e2ff56ea...	Chicago Medallion Management	15.1	5.0
74605d6aa0c8ba08190a5824f7...	Blue Ribbon Taxi Association Inc.	0.2	3.7
abb33898b8d70d22237631f6bd...	Chicago Medallion Management	3.4	3.1
e6a8d59b08b735bf949c799157...	Taxi Affiliation Services	0.2	2.6
d24314a66ebc6319a50cc335d6...	Taxi Affiliation Services	0.1	2.3
9d20d7617e35a8d763ca0bbe3b...	Northwest Management LLC	4.5	3.0
1226e3d8b86299171525b37f43...	Choice Taxi Association	0.3	1.1
7985168ea616aa1c4437d4ebe4...	KOAM Taxi Association	13.2	5.7
365689b9f3107b807470fe16b7...	Taxi Affiliation Services	0.2	1.4
8c4cce532e3fa081753ea28c1b...	Taxi Affiliation Services	1.3	20.0
627de0f7c9251f9731fe27af6bb...	Taxi Affiliation Services	2.7	2.0
705cc88d7a216145f6c762aa70...	Dispatch Taxi Affiliation	3.7	2.3
01dfe8a384fbd91738442964e7...	Dispatch Taxi Affiliation	1.2	4.0
493b6af5931ea2c7c6a82d9d6e...	Taxi Affiliation Services	0.9	7.0
e5a4715f2ec431f404f71c7e4d0...	Choice Taxi Association	2.7	1.0
9aabfe03b50f6d742bc86499ea...	Choice Taxi Association	13.4	13.0
e61ce97d61bec30e506e2ff56ea...	Chicago Medallion Management	2.2	2.0

Figure: Chicago trips dataset, source (Chicago)

Objective: *explain the trip's tip with distance and company "quality".*

With Linear Regression as the machine learning model.

Linear Regression on the Chicago dataset

Model

$$Tip_{estimated} = a_{company} \times distance + b$$

One slope per company; Intercept is shared among all the taxis.

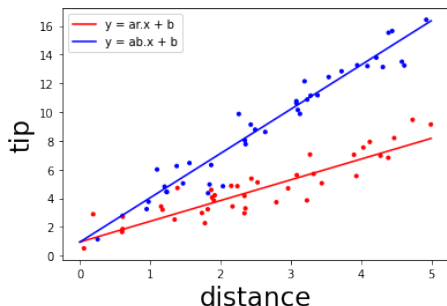
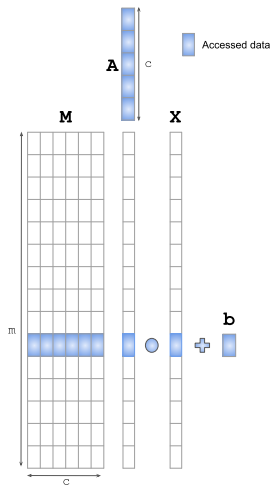


Figure: Model

Comparing the matrix approach (ML Libraries) and relational one

Approach



$$(M.A) \circ X + b$$

\circ is the point-wise product

Figure: Matrix approach

Approach

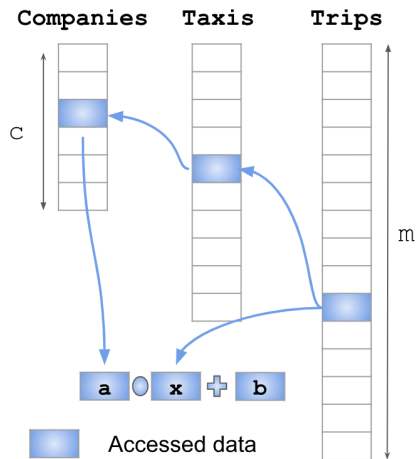


Figure: Relational approach

Approach

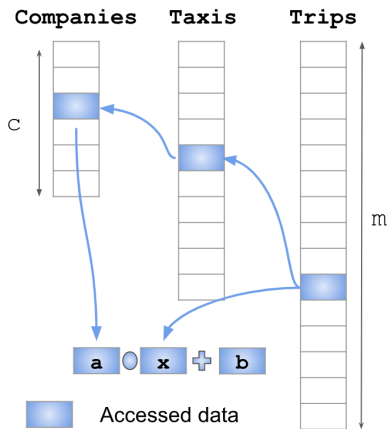
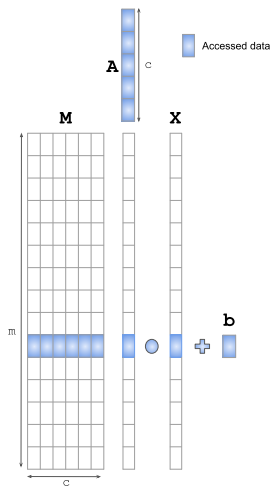


Figure: Relational approach

Figure: Matrix approach

Model

$$Tip_{estimated} = a_{company} \times distance + b$$

In SQL it gives

```

WITH TaxisWithSlope AS (
  SELECT *
  FROM Taxis
  INNER JOIN Companies
  ON Taxis.company = Companies.company)

SELECT
  tripId,
  POWER(Estimated - tip, 2) AS Loss
FROM (
  SELECT
    Trips.*,
    TaxisWithSlope.slope * Trips.distance + @intercept AS Estimated
  FROM Trips
  INNER JOIN TaxisWithSlope
  ON Trips.taxiId = TaxisWithSlope.taxiId )
AS Observations;

```

SQL query of our model.

⚠ Trips = Observations

$$Loss = \sum_{t \in Trips} loss_t = \sum_{t \in Trips} f(data_t) = \sum_{t \in Trips} (a_{comp_t} \times dist_t + b - tip_t)^2$$

with

$$f(a, x, b, y) = (ax + b - y)^2$$

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with

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Then it is feasible to compute gradients!

$$\frac{\partial f}{\partial a} \quad ; \quad \frac{\partial f}{\partial x} \quad ; \quad \frac{\partial f}{\partial b} \quad ; \quad \frac{\partial f}{\partial y}$$

Constraint 2

f has to be differentiable.

$$f(a, x, b, y) = (ax + b - y)^2$$

Figure: Inputs origin.

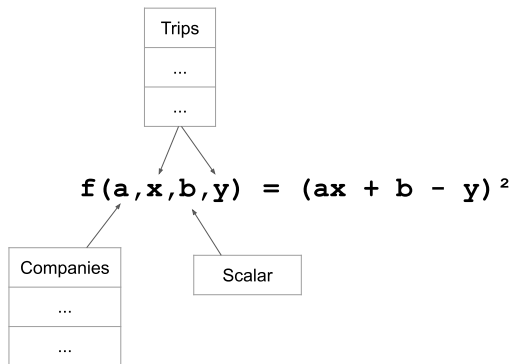


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Math

Relational

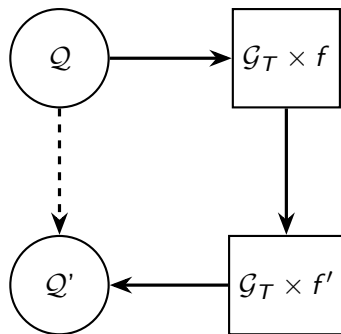
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Q : query
 \mathcal{G}_T : tables graph
 f : loss function

Figure: Path to Differentiating Relational Queries.

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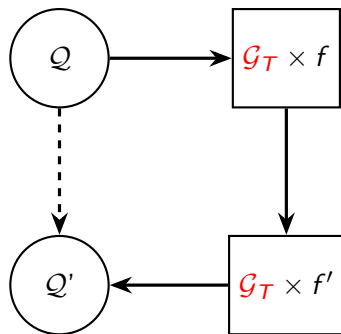
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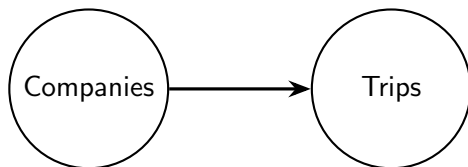


Figure: Graph from our linear regression model.

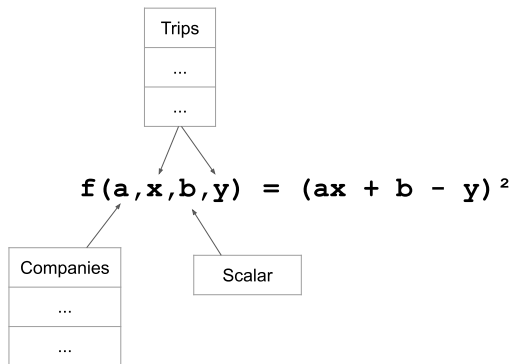


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Tables Relations

Let be

- T a table used in the query
- $T.A$ be a column of T
- a the input of f representing $T.A$

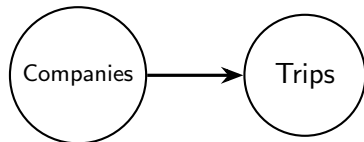
If T (transitively) broadcasts into *Observations* then a the input of f representing $T.A$ is a **scalar**.

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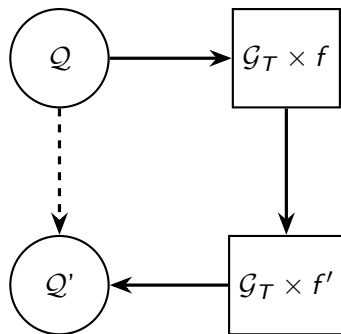
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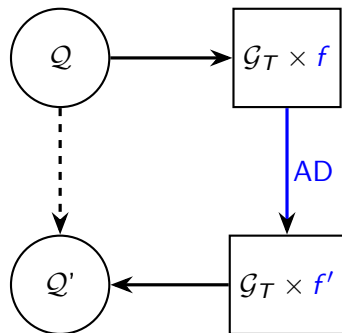
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Approach



Q : query

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AD : Automatic Differentiation

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Automatic Differentiation

P a program that apply the mathematical function f to its inputs.

Automatic Differentiation constructs program the program P' that apply f' to its inputs.

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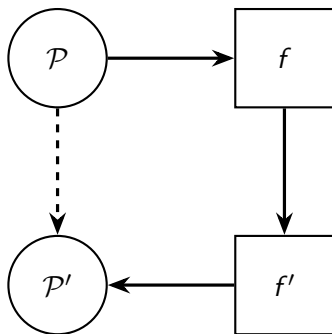


Figure: Automatic Differentiation.

Automatic Differentiation

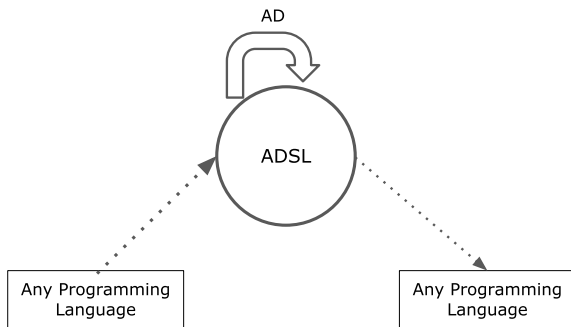
- Fortran, C: Tapenade
- Python: Tangent, Myia
- Julia: Zygote
- F#: DiffSharp
- ...

Automatic Differentiation

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 - ...
-
- not differentiating a specific programming language.
 - define a narrowed programming language: **ADSL**. Similar to (Abadi 2019) (Hu 2020) (Mak 2020).

ADSL is **closed by differentiation**

Automatic Differentiation compilation



We can use this pipeline to differentiate a function written in any programming language *You just need to pay the price of compilation.*

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Implementation

This work has been implemented at Lokad:

- on the DSL *Envision*
- live in production

Optimization through gradient descent is used daily and triggers orders on millions of SKUs.

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Conclusion

In this work we've presented a framework on automatic differentiation on relational queries.

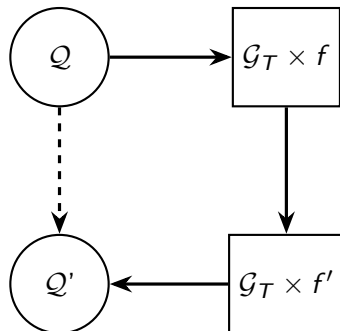


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Conclusion

This will unlock ML model construction and optimisation in databases.

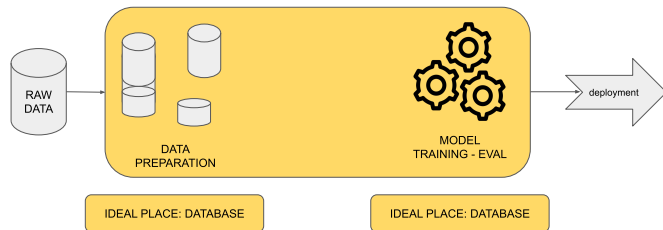


Figure: Proposed Pipeline.

Thanks for listening!

- [Abadi 2019] Martín Abadi et Gordon Plotkin. *A simple differentiable programming language*. Proceedings of the ACM on Programming Languages, vol. 4, pages 1–28, 12 2019.
- [Chicago] City Of Chicago. *image*. <https://data.cityofchicago.org/Transportation/Taxi-Trips/wrvz-psew>. Accessed: 2021-07-13.
- [Hu 2020] Y. Hu, L. Anderson, Tzu-Mao Li, Q. Sun, N. Carr, Jonathan Ragan-Kelley et F. Durand. *DiffTaichi: Differentiable Programming for Physical Simulation*. ArXiv, vol. abs/1910.00935, 2020.
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<https://www.sciencemag.org/news/2018/05/ai-researchers-allege-machine-learning-alchemy>. Accessed: 2021-07-15.
- [Mak 2020] Carol Mak et C. Ong. *A Differential-form Pullback Programming Language for Higher-order Reverse-mode Automatic Differentiation*. ArXiv, vol. abs/2002.08241, 2020.
- [Mcscherry 2021] Frank Mcscherry, Derek Murray, Rebecca Isaacs et Michael Isard. *Differential dataflow*. 08 2021.
- [Schüle 2019] Maximilian E. Schüle, Frédéric Simonis, Thomas Heyenbrock, A. Kemper, Stephan Günemann et T. Neumann. *In-Database Machine Learning: Gradient Descent and Tensor Algebra for Main Memory Database Systems*. In BTW, 2019.

[Link to an example](#)

$\langle S \rangle$	$::= .$	
	$\langle v \leftarrow e \rangle$	Variable assignment
	$\langle \text{Cond} (v \ \Psi \ P_T \ P_E \ \Phi) \rangle$	Conditional
	$\langle \text{For} (\chi \ P \ \Xi) \rangle$	Loop
	$\langle \text{Return } v \rangle$	Output of a program
$\langle e \rangle$	$::= .$	
	$\langle v \rangle$	Variable
	$\langle f \rangle$	Scalar
	$\langle b \rangle$	Boolean
	$\langle v + w \rangle$	Variable Addition
	$\langle \text{Call1 } op \ v \rangle$	Function Call
	$\langle \text{Call2 } op \ v \ w \rangle$	Function Call (2 parameters)
	$\langle \text{Param } i \rangle$	Parameter access
	$\langle \text{Const } i \rangle$	Constant access
	$\langle v \triangleleft \beta \rangle$	Broadcast Projector
	$\langle v \triangleright \alpha \rangle$	Aggregation Projector
	$\langle \text{Pred} \rangle$	Predicate

$\langle \textit{Pred} \rangle ::= .$

- | $\langle \textit{And } v \ w \rangle$
- | $\langle \textit{Or } v \ w \rangle$
- | $\langle \textit{Not } v \rangle$
- | $\langle v < w \rangle$
- | $\langle v \leq w \rangle$

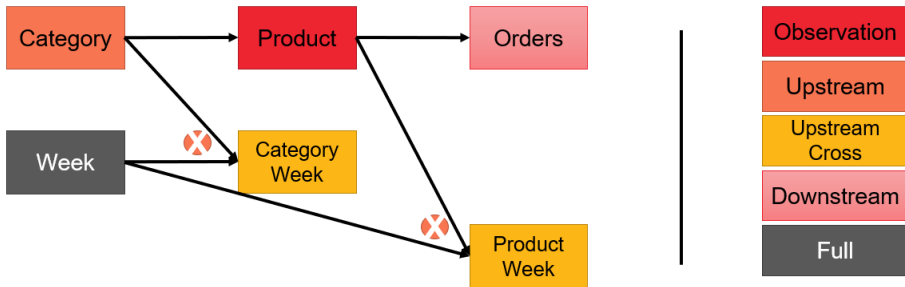


Figure: PolyStar

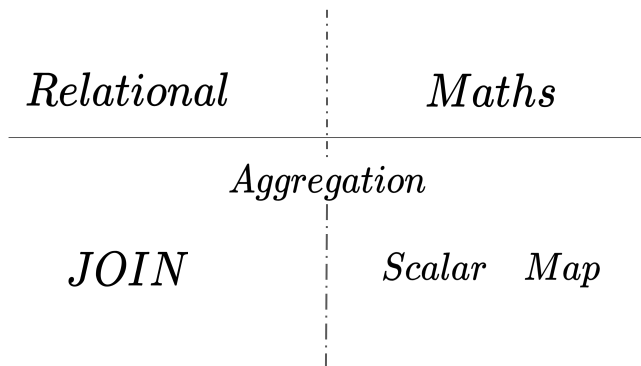


Figure: Relational - Math decomposition